| Days | | Monday, 1 | 2 October | | | Tuesday, | 13 October | | Wednesday, 14 October | | | |
|-------------|-----------------------|------------------------|------------------------|------------------------|-----------------------|---|------------------------------------|------------------------|-----------------------|------------------------|--------------------------|------------------------|
| Room | 201 202 203 204 | | | | | 202 | 203 | 204 | 201 | 202 | 203 | 204 |
| 9:00-9:30 | | Regis | tration | | Registration | | | Registration | | | | |
| 9:30-9:45 | Opening (| Main Hall (Prof. | Ichiro Hagiwara, I | Meiji Univ.) | | | | | | | | |
| 9:45-10:45 | Session 1 RS (3) | Session 2 OS12 (3) | Session 3 OS2 (3) | Session 4 OS11 (3) | Session 17 OS5 (3) | Session 18 OS4 (3) | Session 19 OS1 (3) | Session 20 OS11 (3) | Session 33 OS6 (3) | Session 34 OS13 (3) | Session 35 OS1 (3) | Session 36 OS18 (3) |
| 10:45-11:00 | | Bro | eak | | Break | | | | | Bre | eak | |
| 11:00-12:00 | Session 5 RS (4) | Session 6 OS12 (3) | Session 7 OS2 (3) | Session 8 OS11 (3) | Session 21 OS5 (3) | Session 22 OS4 (3) | Session 23 OS1 (3) | Session 24 OS11 (3) | Session 37 OS6 (3) | Session 38 OS16 (3) | Session 39 OS1 (3) | Session 40 OS18 (2) |
| 12:00-13:30 | | Lui | l nch | | | Lunch | | | Lunch | | | |
| 13:30-13:45 | Address 1 | | Shunro Endo, To | vama Univ) | Address 2 @ M | Address 2 @ Main Hall (Prof. Masaru Ishizuka, Toyama Pref. Univ.) | | | | | | |
| 13:45-14:30 | | , | . Shihoko Ishii, Ur | , | (Prof. S | Plenary talk 2 Siegfried M. Rump | 2 @ Main Hall , Hamburg Univ. o | f Tech.) | | | | Session 44 OS15 (4) |
| 14:30-14:45 | | Bro | eak | | | Break | | | | | | |
| 14:45-15:45 | Session 9 OS3 (3) | Session 10 OS12 (2) | Session 11 OS2 (3) | Session 12 OS11 (3) | Session 25 OS5 (3) | Session 26 OS4 (3) | Session 27 OS1 (3) | Session 28 OS17 (3) | Closing @ Ma | | eak 0 (Prof. Osamu Or | no, Meiji Univ.) |
| 15:45-16:00 | | Bre | eak | L | Break | | | Break | | | | |
| 16:00-17:00 | Session 13 OS3 (4) | Session 14 OS7 (4) | Session 15 OS19 (4) | Session 16 OS11 (3) | Session 29 OS5 (3) | Session 30 OS8 (4) | Session 31 OS1 (3) | Session 32 | | | | |
| | | | | | | | | | | - | | - |
| | | | | | | Reception (| 18:00-19:30) | | | | | |

| Session | Submittion | ID | Title | Authors |
|------------------------------------|--------------|---------|---|--|
| OS1: Numerical Simulation a | | | | |
| | OS1 | 4026 | Visualization of Large-scale Time-varying Unstructured Volume Data with Interactive Particle-based Rendering | Kun Zhao (Graduate School of Engineering, Kyoto University), Naohisa Sakamoto (Institute for Liberal Arts and Sciences, Kyo University), Koji Koyamada (Academic Center for Computing and Media Studies, Kyoto University) |
| Session 19 9:45-10:45, 13 Oct. | OS1 | 4061 | Electromagnetic wave propagation simulation in corrugated waveguide – Influence of miter bend on transmission mode – | Yoshihisa Fujita (Department of Energy Engineering and Science, Nagoya University), Soichiro Ikuno (School of Computer Sc Tokyo University of Technology), Shin Kubo (Department of Energy Engineering and Science, Nagoya University, NIFS), Hirot Nakamura (Department of Energy Engineering and Science, Nagoya University, NIFS) |
| | OS1 | 4069 | Sputtering yield of argon irradiation onto tungsten nano-structure | Hiroaki Nakamura (National Institute for Fusion Science), Seiki Saito (Kushiro National College of Technology), Atsushi M. Ito Institute for Fusion Science), Arimichi Takayama (National Institute for Fusion Science) |
| | OS1 | 4091 | "Atmosphereoceanmarine ecosystem" synthesized simulation using a global coupled data assimilation system | Shiro Nishikawa (JAMSTEC, Japan), Yoichi Ishikawa (JAMSTEC, Japan), Shuhei Masuda (JAMSTEC, Japan), Haruka Nishiki (JAMSTEC, Japan), Hiromichi Igarashi (JAMSTEC, Japan) |
| Session 23 11:00-12:00, 13 Oct. | OS1 | 4099 | Bubble formation in tungsten material under energetic helium ion injection | Seiki Saito (Department of Electrical Engineering, Institute of Technology, Kushiro College), Masayuki Tokitani (Department of Pflasma Research, National Institute for Fusion Science), Hiroaki Nakamura (Department of Helical Plasma Research, Nationa for Fusion Science) |
| | OS1 | 4102 | Investigation of Variable Preconditioned Krylov Subspace Method for Linear System Obtained by Extended Element-Free Galerkin Method | Soichiro Ikuno (Tokyo University of Technology), Gong Chen (Tokyo University of Technology), Taku Itoh (Nihon University) |
| | OS1 | 4134 | Real-time particle-based fluid simulation with interactively deformable obstacles | Koki Makishima (Graduate School of Information Science and Engineering, Ritsumeikan University), Susumu Nakata (College Information Science and Engineering, Ritsumeikan University) |
| Session 27 14:45-15:45, 13 Oct. | OS1 | 4140 | Development of the Shifted Block BiCGGR method and accuracy improvement of approximate solutions | Hiroto Tadano (Department of Computer Science, University of Tsukuba), Shusaku Saito (Department of Computer Science, L of Tsukuba), Akira Imakura (Department of Computer Science, University of Tsukuba) |
| | OS1 | 4169 | Construction of a Virtual Space for Kyoto Gion Festival | Kohki Kurokawa (Ritsumeikan University), Ken Ishikawa (Ritsumeikan University), Wang Sheng (Ritsumeikan University), Kyo Hasegawa (Ritsumeikan University), Rui Xu (Ritsumeikan University), Satoshi Tanaka (Ritsumeikan University) |
| | OS1 | 4182 | Visualization of Large-scale Point-based Volume Data Generated by Particle Fluid Simulation | Takafumi Kishida (Ritsumeikan University), Kentarou Tanaka (Ritsumeikan University), Satoshi Tanaka (Ritsumeikan Universit Hasegawa (Ritsumeikan University), Xu Rui (Ritsumeikan University), Kohel Murotani (The University of Tokyo), Seiichi Koshi: University of Tokyo) |
| Session 31 16:00-17:00, 13 Oct. | OS1 | 4183 | Comparative visualization of plasma-plume collisions focusing on coincidence of multiple datasets | Yushi Uenoyama (Ritsumeikan University), Syuhei Kawata (Ritsumeikan University), Taku Kusanagi (Ritsumeikan University), Hasegawa (Ritsumeikan University), Rui Xu (Ritsumeikan University), Satoshi Tanaka (Ritsumeikan University), Toshinori Yat (RIKEN), Kazuo Tanaka (Osaka University) |
| | OS1 | 4185 | 3D Transparent Viewing of Ultra-high-resolution Photo Images Fused with Point Data acquired by Measuring a 3D Cultural Heritage | Ryohei Umegaki (Graduate School of Information Science & Engineering Ritsumeikan University), Rui Xu (College of Informat Science & Engineering, Ritsumeikan University), Kyoko Hasegawa (College of Information Science & Engineering, Ritsumeikan University), Satoshi Tanaka (College of Information Science & Engineering, Ritsumeikan University) |
| | OS1 | 4189 | FDM Simulation of Inactivation of Detrimental Microorganism in High Voltage Field | Hideki Kawaguchi (Muroran Institute of Technology), Kohki Satoh (Muroran Institute of Technology), Igor V. Timoshkin (Univer Strathclyde), Martin Given (University of Strathclyde), Scott J. Macgregor (University of Strathclyde) |
| Session 35 9:45-10:45, 14 Oct. | OS1 | 4207 | Particle-based rendering for large-scale polygon meshes | Ryota Aoki (Ritsumeikan University), Kyoko Hasegawa (Ritsumeikan University), Hideaki Miyachi (Cybernet Systems), Kayako Katsuyama (ARK Information Systems), Satoshi Tanaka (Ritsumeikan University) |
| | OS1 | 4209 | Highlighting polygon edges in transparent visualization of large-scale polygon meshes application to visualize high-energy particle detectors | Ryoji Sanagawa, Satoshi Tanaka, Kyoko Hasegawa (Graduate School of Information Science and Engineering, College of Info Science and Engineering, Ritsumeikan University) |
| | OS1 | 4224 | 3D Volumetric Model Reconstruction from Tomographic Image Data of Honeybee Standard Brain, Part II | Ayumu Saitoh (Yamagata University), Atsushi Komano (Yumebishi electric Co., Ltd.), Teijiro Isokawa (University of Hyogo), Hi Ikeno (University of Hyogo), Nobuyuki Matsui (University of Hyogo) |
| Session 39 11:00-12:00, 14 Oct. | OS1 | 4244 | Comparative Fused Visualization of Plasma-plume Experiment and Simulation | Shuhei Kawata (Ritsumeikan University), Yushi Uenoyama (Ritsumeikan University), Taku Kusanagi (Ritsumeikan University), Hasegawa (Ritsumeikan University, Ritsumeikan University), Satoshi Tanaka (Ritsumeikan University), Toshinori Yat (RIKEN SPring-8 Center), Kazuo Tanaka (Osaka University) |
| | OS1 | 4269 | High-Speed Method for Analyzing Shielding Current Density in HTS with Cracks: Implementation of H-Matrix Method to GMRES | Teruou Takayama (Yamagata University), Ayumu Saitoh (Yamagata University), Atsushi Kamitani (Yamagata University) |
| | OS1 | 4328 | Monte Carlo simulation for thermal assisted magnet-ization reversal process of cylindrical cluster | Kenichi Terashima (Faculty of Symbiotic Systems Science, Fukushima University), Katsuhiko Yamaguchi (Faculty of Symbiotii Science, Fukushima University) |
| Session 43 13:30-14:30, 14 Oct. | OS1 | 4339 | Numerical Investigation of Preconditioning for Iterative Methods in Linear Systems Obtained by Extended Element-Free Galerkin Method | Taku Itoh (College of Industrial Technology, Nihon University, Japan), Ayumu Saltoh (Graduate School of Science and Engine Yamagata University, Japan), Soichiro Ikuno (School of Computer Science, Tokyo University of Technology, Japan), Atsushi k (Graduate School of Science and Engineering, Yamagata University, Japan) |
| | RS16 | 4617 | Shear stress and Mises stress of a subduction zone as inferred from elastic plate models | Mitsuru Yoshida (Fortran Plan Office) |
| OS2: Multi dimensional comm | nunication n | etworks | | |
| _ | OS2 | 4039 | Signal Path Loss through the Human Arm by Galvanic Coupling Intra-body Communication Using Non-Contact Electrodes on the Transmission Side | Kenichi Ito (Niigata Institute of Technology), Yu Hotta (Niigata Institute of Technology) |
| Session 3 9:45-10:45, 12 Oct. | OS2 | 4077 | Application of Cellular System with Direct Communication to a Disaster Situation | Tatsuya Kabasawa (Dept. of Electrical and Electronic Systems Engineering, National Institute of Technology, Nagaoka Collegi Keisuke Nakano (Graduate School of Science and Technology, Niigata University, Japan) |
| | OS2 | 4121 | Effectiveness of fixed channel assignment strategy on multi-hop wireless networks | |
| Session 7 11:00-12:00, 12 Oct. | OS2 | 4396 | Adaptive Modified Sign-Algorithm Equalizer for DS-CDMA Communication System Based on Adaptive Laguerre Lattice Filter | M. Lertwateechakul (Faculty of Engineering, King Mongkut's Institute of Technology Ladkrabang, Bangkok 10520, Thailand.), Benjangkaprasert (Faculty of Engineering, King Mongkut's Institute of Technology Ladkrabang, Bangkok 10520, Thailand) |
| | OS2 | 4403 | Analysis of relief goods delivery and information sharing by epidemic transmission in disaster areas | Kazuyuki Miyakita (Center for Academic Information Service, Niigata University), Masashi Yamashita (Department of Informati Engineering, Niigata University), Keisuke Nakano (Department of Information Engineering, Niigata University) |
| | OS2 | 4426 | A Consideration on Arrangement of Places where Information is Floated | Naoyuki Karasawa (Department of Information Engineering, Niigata University), Keisuke Nakano (Department of Information Engineering, Niigata University), Kazuyuki Miyakita (Center for Academic Information Service, Niigata University), Hiroshi Tam (Department of Electrical, Electronic, and Communication Engineering, Chuo University) |
| Session 11 14:45-15:45, 12 Oct. | OS2 | 4443 | A Novel Minimum WiFi Throughput Estimation for WiFi Offloading | Nam Nguyen (Graduate School of Information and Telecommunication Studies, Waseda University), Takuro Sato (Graduate S Information and Telecommunication Studies, Waseda University) |
| | OS2 | 4452 | Business trends of GSM in consideration of IPR issue and royalty strategy | Kasumi Haruta (Waseda University Graduate school of Fundamental and Science Engineering), Arifuzzaman. M (Waseda Uni Graduate School of Global Information and Telecommunication Studies), Zhenyu Zhou (North China Power electric University) Sato (Waseda University Graduate school of Fundamental and Science Engineering) |
| | OS2 | 4469 | The Simulation of Surface Plasmon Polariton based Photonic Integrated Devices by Modified Add-Drop | Nopparat Thammawongsa (Hybrid Computing Research Laboratory (HCRL), Faculty of Engineering, King Mongkut's Institute Technology Laddrabang, Bangkok 16520, Thaliandy, Khanthamou Luangraysapana (Hybrid Computing Research Horboratory (HC Faculty of Engineering, King Mongkut's Institute of Technology Ladkrabang, Bangkok 10520, Thaliand), Somsak Mitatha (Hyb Computing Research Laboratory (HCRL), Faculty of Engineering, King Mongkut's Institute of Technology Ladkrabang, Bangko Thaliand), |

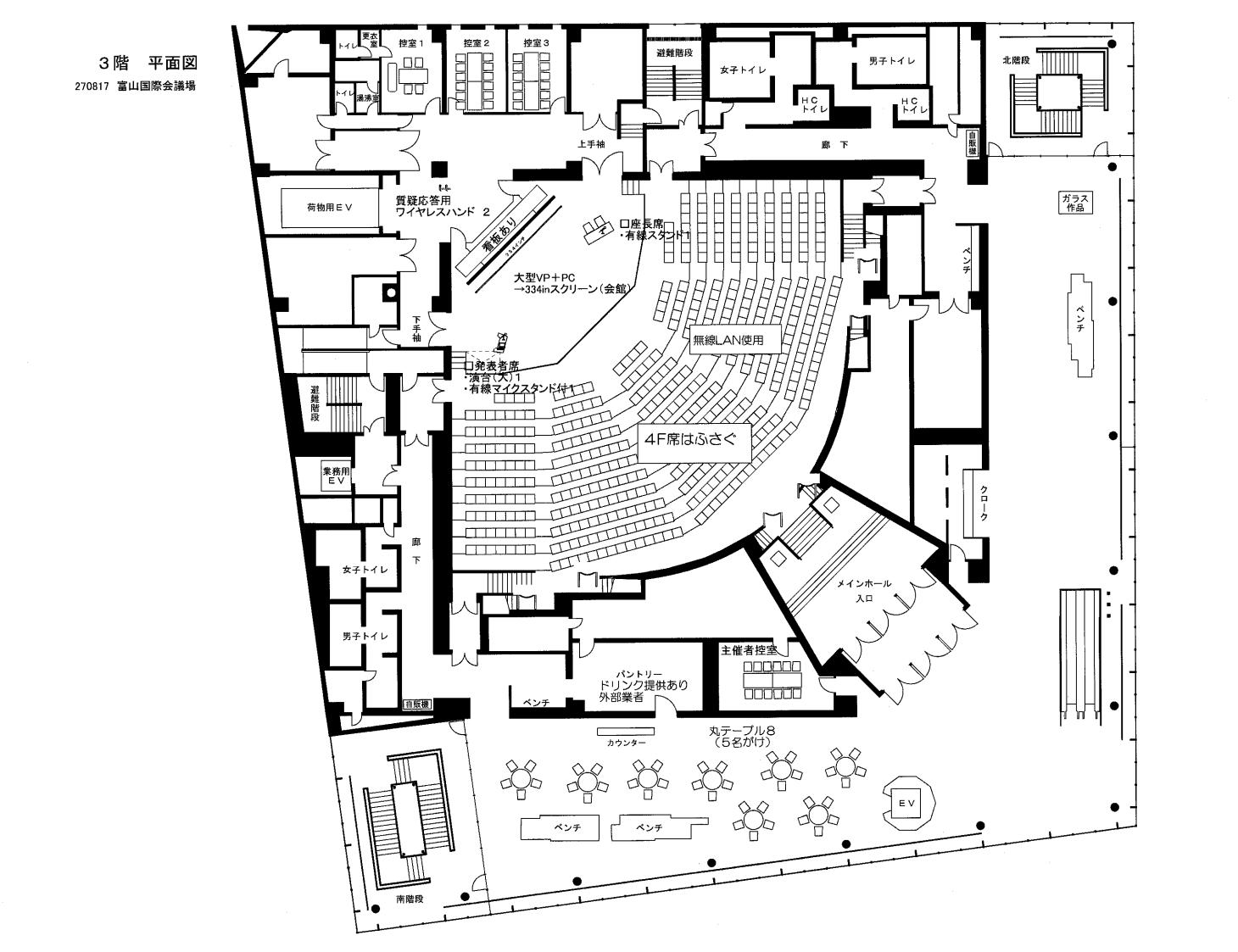
| OS3: Numerical Computation | ns | | | |
|------------------------------------|---------------|----------|---|--|
| 000. Numerical computation | OS3 | 4075 | The Development of the Chaotic Block Cipher | Yasuaki Tsuruoka (Graduate School of Science and Technology, Meiji University, Japan), Tomofumi Nakasone (Graduate School of Science and Technology, Meiji University, Japan), Kyohei Kamiyama (School of Science and Technology, Meiji University, Japan) Hiroyuki Kamata (School of Science and Technology, Meiji University, Japan) |
| Session 9 14:45-15:45, 12 Oct. | OS3 | 4387 | Numerical verification for positiveness of solutions to self-adjoint elliptic problems | Kazuaki (Tanaka), Kouta (Sekine), Makoto (Mizuguchi), Shin'ichi (Oishi) |
| | OS3 | 4392 | Verified computations for solutions of semilinear heat equations using an analytic semigroup generated by a self-adjoint operator | Makoto Mizuguchi (Graduate School of Fundamental Science and Engineering, Waseda University), Kouta Sekine (Departmer Applied Mathematics, Faculty of Science and Engineering, Waseda University), Aktioshi Takayasu (Research Institute for Scie Engineering, Waseda University), Takayuki Kubo (Institute of Mathematics, Livriersity of Tsukuba), Shin'ichi Oishi (Departmen Applied Mathematics, Science and Engineering, Waseda University and CREST, JST) |
| | OS3 | 4393 | Framework for verified lower eigenvalue bound for self-adjoint differential operators | Xuefeng Liu (Niigata University), |
| Session 13 | OS3 | 4447 | Numerical existence theorem for solutions of semilinear parabolic equations using the evolution operator | Akitoshi Takayasu (Research Institute for Science and Engineering, Waseda University), Makoto Mizuguchi (Graduate School Fundamental Science and Engineering, Waseda University), Takayuki Kubo (Institute of Mathematics, University of Tsukuba), Oishi (Department of Applied Mathematics, Waseda University and CREST, JST) |
| 16:00-17:20, 12 Oct. | OS3 | 4455 | Fast Enclosures of Solutions of Linear Systems with H-matrices | Atsushi Minamihata (Waseda University), Takeshi Ogita (Tokyo Woman's Christian University and JST CREST), Shin'ichi Oist (Waseda University and JST CREST) |
| | OS3 | 4147 | Verified Numerical Computations for Convex Hull | Katsuhisa Ozaki (College of Systems Engineering and Science, Shibaura Institute of Technology), Takeshi Ogita (School of Al Sciences, Tokyo Woman's Christian University), Shinichi Oishi (Faculty of Science and Engineering, Waseda University) |
| OS4: Simulation and Visualiz | zation in Imn | nersive | Virtual Environment | |
| | OS4 | 4152 | Thai Martial Art Training Game with Kinect | Pikulkaew Tangtisanon (KMITL) |
| Session 18 9:45-10:45, 13 Oct. | OS4 | 4154 | Comparative analysis of impression of rooms with different kinds of windows between scale-model and virtual conditions | Michiko Ohkura (Shibaura Institute of Technology), Wataru Morishita (Shibaura Institute of Technology), Kodai Ito (NTT Softwa Corporation), Yae Aoyagi (Shibaura Institute of Technology), Yoko Watanabe (Shibaura Institute of Technology) |
| | OS4 | 4163 | Driving Assistance and Warning System on Android | Patthawee Narkbutr (KMITL), Pirapat Paparn (KMITL), Chompoonuch Jinjakam (KMITL) |
| | OS4 | 4292 | Artificial jellyfish: evolutionary simulation and foveated rendering | Vladimir Lazunin (Faculty of Computer and Information Science, Hosei University), Vladimir Savchenko (Faculty of Computer a Information Science, Hosei University) |
| Session 22 10:00-11:00, 13 Oct. | OS4 | 4343 | A study of Smart Farm System assist by data visualization for a precision agriculture. | Amnach Khawne (King Mongkut's Institute of Technology Ladkrabang) |
| | OS4 | 4370 | Porting of visualization software to Oculus Rift | Shintaro Kawahara (JAMSTEC), Akira Kageyama (Kobe University) |
| | OS4 | 4506 | Computational Analysis of Waveform Distortion for Ultra Wideband Impulse Radio Transmission | Phouthong Southisombath (King Mongkut's Institute of Technology Ladkrabang), Khamphoui Southisombath (Department of E and Telecommunication, National University of Laos), Sathaporn Promwong (King Mongkut's Institute of Technology Ladkrabs |
| Session 26 14:45-15:45, 13 Oct. | OS4 | 4508 | FGPA Evaluation of a Time Domain RS Decoder | Kentaroh Kato (National Institute of Technology, Tsuruoka College), Somsak Choomchuay (King Mongkut's Institute of Techno Ladkrabang) |
| | OS4 | 4510 | Arrhythmia ECG Classification Using Adaptive FCM and Fisher's LDA | Somsanouk Pathournvanh (National University of Laos), Somsak Choomchuay (King Mongkut's Institute of Technology Ladkra Kazuhiko Hamamoto (Tokai University) |
| S5: Computational Electron | magnetism a | nd Its / | Applications | |
| | OS5 | 4083 | Development of 3-D Modeller for FDTD Method Using Motion Sensor Tool | Masanori Ishida (Muroran Institute of Technology), Hideki Kawaguchi (Muroran Institute of Technology) |
| Session 17 9:45-10:45, 13 Oct. | OS5 | 4128 | Optimization of Synchronous Reluctance Motors Considering Uncertainties in Magnetic Property | Yuki Hidaka (Mitsubishi Electric Corporation,Hokkaido University), Hajime Igarashi (Hokkaido University) |
| | OS5 | 4136 | An Investigation of Microwave Thermal Therapy for Narrowed Male Urinary Tract using Encapsulated-expandable Balloon Coaxial Antenna | Pattarapong Phasukkit (Faculty of Engineering, King Mongkut's Institute of Technology Ladkrabang, Bangkok, Thailand), Sind Jandang (Faculty of Engineering, King Mongkut s Institute of Technology Ladkrabang, Bangkok, Thailand), Supan Tungitkuso (Faculty of Engineering, King Mongkut's Institute of Technology Ladkrabang, Bangkok, Thailand), Arthorn Sanpanich (Faculty Engineering, King Mongkut's Institute of Technology Ladkrabang, Bangkok, Thailand) |
| | OS5 | 4150 | Examination of the Current Dependence of Power Factor and Power Transfer Efficiency for a Non-contact Charger | Daigo Yonetsu (Kansai University), Yasushi Yamamoto (Kansai University) |
| Session 21 11:00-12:00, 13 Oct. | OS5 | 4223 | Three Dimensional Analysis of Structural Coloration in Subwavelength Gratings | Hideaki Wakabayashi (Okayama Prefectural University), Masamitsu Asai (Kindal University), Jiro Yamakita (Okayama Prefect University) |
| | OS5 | 4250 | Implementation and Acceleration of the HDDM for the Electromagnetic Field Problem (2nd report) | Shin-ichiro Sugimoto (Tokyo University of Science, Suwa) |
| | OS5 | 4274 | Modeling of Electromagnetic Wave Penetration in Human Body due to Emssion from Industrail Elec-tromagnetic Field Source | Wara Suwansin, (Pattarapong Phasukkit), (Supan Tungitkusolmun) |
| Session 25 14:45-15:45, 13 Oct. | OS5 | 4296 | Design and analysis of dielectric cover for planar waveguide slot array antenna | Keiichi Itoh (Akita National College of Technology), Katsumasa Miyata (Akita National College of Technology), Hajime Igarashi (Hokkaido University) |
| | OS5 | 4301 | Numerical Study on Small Quasi Isotropic Particles for Chiral Media with Fine Granularity | Masamitsu Asai (Kinki University), Hideaki Wakabayashi (Okayama Prefecture University), Jiro Yamakita (Okayama Prefecture University), Keiji Matsumoto (Osaka Sangyo University) |
| | OS5 | 4308 | High-accuracy Analysis of Finite Element Full-Wave Electromagnetic Field Using Voxel Mesh Models | Amane Takei (Department of Electrical and System Engineering, Faculty of Engineering, University of Miyazaki) |
| Session 29 16:00-17:00, 13 Oct. | OS5 | 4360 | Time-dependent FEA of plasmonic polariton | Masanori Hashiguchi (Keisoku Engineering System Co.,Ltd.) |
| | OS5 | 4446 | Comparison generalized quantum key distribution (QKD) between using PANDA ring resonator and series micro ring resonator applies for communication security | Xaythavy Louangvilay (Hybrid Computing Research Laboratory, Faculty of Engineering, King Mongkut's Institute of Technolog Ladkrabang, Bangkok, 10520, Thailand), Somsak Mitatha (Hybrid Computing Research Laboratory, Faculty of Engineering, Ki Mongkut's Institute of Technology Ladkrabang, Bangkok, 10520, Thailand), Masahirio Yoshids (School of Information Technol Telecommunication Engineering, Tokai University, Japan), Noriyuki Komine (School of Information Technology and Telecomm Engineering, Tokai University, Japan), Preecha Yupapin (Nanoscale Science and Engineering Research Alliance, Faculty of Sking Mongkut's Institute of Technology Ladkrabang, Bangkok 10520, Thailand) |

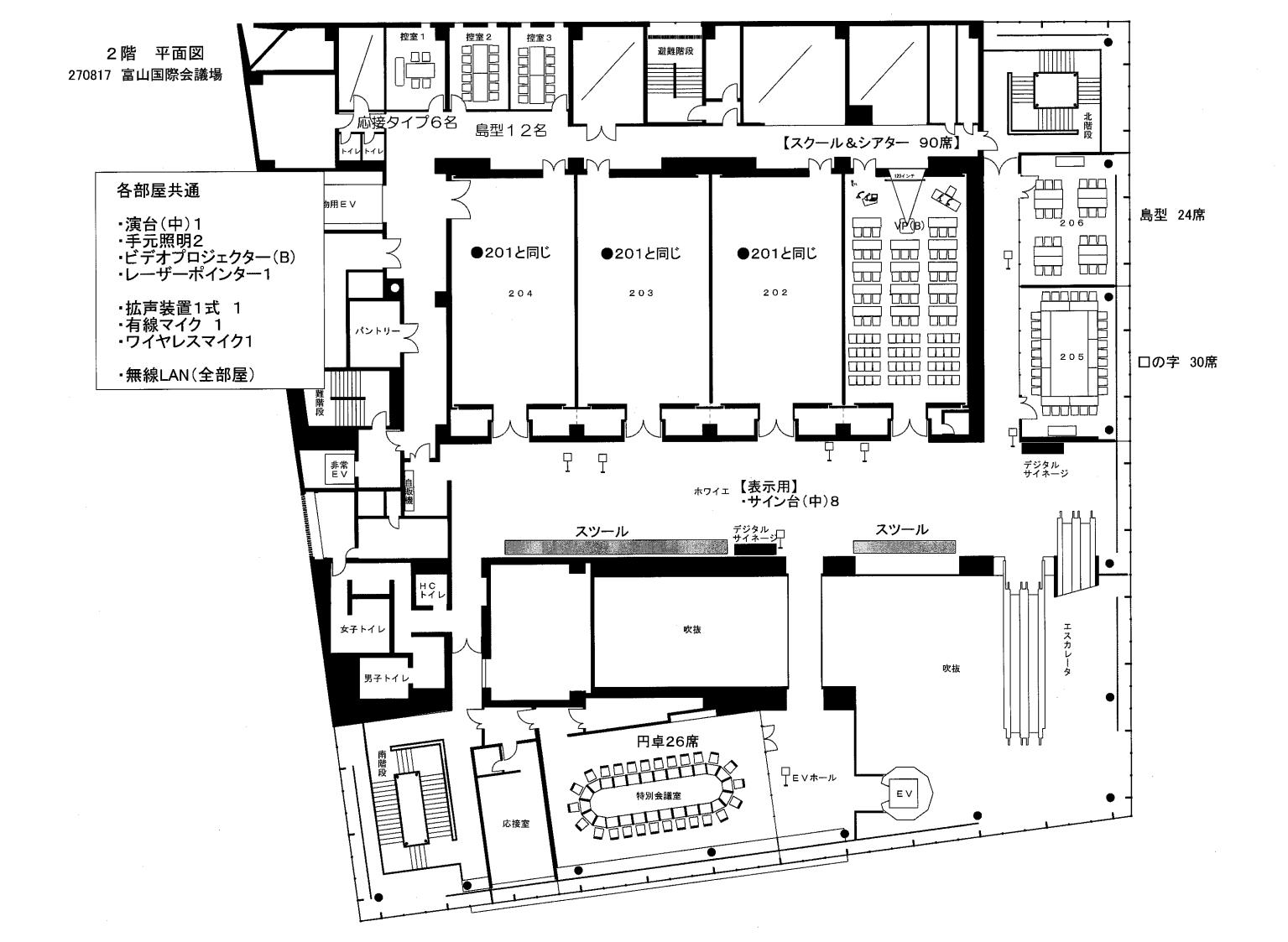
| OS6: Simulation Technology | in Diversifie | d Highe | er Education | | | | | |
|------------------------------------|---------------|---------|--|--|--|--|--|--|
| | OS6 | 4056 | Virtual Group Managing Tutor for Collaborative e-Learning System | Toshiyuki Tojo (Meiji University), Osamu Ono (Meiji University) | | | | |
| Session 33 9:45-10:45, 14 Oct. | OS6 | 4120 | Development of a Computer Simulation Platform for Learning Constructive Approach of Animal Behaviors | Toshiaki Yokoi (Tokyo City University) | | | | |
| | OS6 | 4126 | Visualization of Complex Quasi-Periodic Oscillation -Visualization of Phenomenon Composed by Non-Resonance Oscillations- | Kyohei Kamiyama (Meiji University), Motomasa Komuro (Teikyo University of Science), Tetsuro Endo (Meiji University) | | | | |
| | OS6 | 4373 | The Simulation Technology of the model following control—On the view of the education— | Hiroki-Shibasaki (Meiji University), Takehito-Fujio (Meiji University), Ryo Tanaka (Meiji University), Osamu Ono (Meiji Universit | | | | |
| Session 37 | OS6 | 4437 | Development of Simulation Model for Autonomous Distributed AGV Systems By Appling Social Force Model | Jie Chen (Osaka Prefecture University), Koji Iwamura (Osaka Prefecture University), Yoshitaka Tanimizu (Osaka Prefecture U Nobuhiro Sugimura (Osaka Prefecture University) | | | | |
| 11:00-12:00, 14 Oct. | OS6 | 4478 | Engaging Engineering Students with Robotics Design Projects: Methods and Case Studies | Yucel Ugurlu (National Instruments Japan Corporation) | | | | |
| | OS6 | 4709 | Simulation technology of the model-following control - On the view of the education | Hiroki Shibasaki (Graduate School of Science and Technology, Meiji University), Osamu Ono (Graduate School of Science an Technology, Meiji University) | | | | |
| OS7: Simplicity in complexity | | | | | | | | |
| | OS7 | 4045 | Computation of transition to turbulence in a pipe with injection based on the Stochastic-Navier-Stokes equation | Akihito Yamasaki (Faculty of Science and Engineering, Waseda University), Ken Naitoh (Faculty of Science and Engineering, University) | | | | |
| Session 14 | OS7 | 4052 | Prediction of death and apparent death: Mathematical conditions derived from the six equation model | Remi Konagaya (Faculty of Science and Engineering, Waseda University), Ken Naitoh (Faculty of Science and Engineering, Vi University) | | | | |
| 16:00-17:20, 12 Oct. | OS7 | 4111 | Dynamical Boundaries for the Transport of Co-Orbital Asteroids in the Circular Restricted Three-Body Problem | Kenta Oshima (Department of Applied Mechanics and Aerospace Engineering, Waseda University), Tomohiro Yanao (Departr Applied Mechanics and Aerospace Engineering, Waseda University) | | | | |
| | OS7 | 4295 | Asymmetric Elasticity and Chiral Specificity in Wrapping and Braiding of DNA | Sosuke Sano (Department of Applied Mechanics and Aerospace Engineering, Waseda University), Tomohiro Yanao (Departm Applied Mechanics and Aerospace Engineering, Waseda University), Kenichi Yoshikawa (Faculty of Life and Medical Science: Doshisha University) | | | | |
| OS8: Kansei and higher brain | n functions | | | | | | | |
| | OS8 | 4161 | Dimensionality Reduction for the Analysis of Iyashi Expressions using Brain Signals | Julian Romero (Meiji Institute for Advanced Study of Mathematical Sciences, Meiji University, Japan), Luis Diago (Interfocus In Institute for Advanced Study of Mathematical Sciences, Meiji University, Japan), Junichi Shinoda (Interfocus Inc. & Meiji Institu Advanced Study of Mathematical Sciences, Meiji University, Japan), Ichiro Hagiwara (Meiji Institute for Advanced Study of Mat Sciences, Meiji University, Japan) | | | | |
| Session 30 16:00-17:20, 13 Oct. | OS8 | 4433 | Evaluation of Exciting Feeling in Driving Simulator by HRV | Yoshihiro Harada (Shibaura Institute of technology), Haruhiko Nakatsuji (Alpine Electronics), Yosuke Tate (Alpine Electronics). Seto (Alpine Electronics), Michiko Ohkura (Shibaura Institute of technology) | | | | |
| 13.00-17.20, 13 Oct. | OS8 | 4460 | Prototyping of an Intuitive Control System for a Power Wheelchair by Using a Simple EEG Recorder and a Smart Glass | Yudai lida (Shibaura Institute of Technology), Ryota Horie (Shibaura Institute of Technology) | | | | |
| | OS8 | 4463 | Analysis of Affective Evaluation for Tactile Material Perception of Bead-coated Resin Surfaces | Michiko Ohkura (Shibaura Institute of Technology), Yuki Kuroda (Shibaura Institute of Technology), Kodai Ito (Shibaura Institut Technology), Masato Takahashi (DIC Corporation), Hiroko Sakurai (DIC Corporation), Kiyotaka Yarimizu (DIC Corporation), A Nakahara (DIC Corporation), Shunichi Nagasawa (DIC Corporation) | | | | |

| Security (1) Control of the Control | 2011: Advanced Computation | anal Mathadi | for Ele | our Cimulations (so organized by the Visualization Society of Inna) | |
|--|----------------------------|--------------|---------|---|--|
| Section 1 40 To 1 40 T | 5011. Advanced Computation | | | Keynote Lecture: Development of High Precision Tsunami Simulation Based on a Hierarchical | Taro Arikawa (Chuo University) |
| Search 2 of the control of the contr | | OS11 | 4268 | | Yuki Koyanagi (Chuo University), Takayuki Oie (Pacific Consultants Co., LTD), Taro Arikawa (Chuo University) |
| Segue 2 To a contract of the c | | OS11 | 4407 | | Katsuhiro Okada (Port and Airport Research Institute), Taro Arikawa (Chuo University) |
| 1900-200 (1900) Septimage | | OS11 | 4087 | | Taichi Kosako (Department of Civil Engineering, Kobe University), Yusuke Uchiyama (Department of Civil Engineering, Kobe I |
| Segment 1 100 100 100 100 100 100 100 100 100 | | OS11 | 4801 | | Yota Suzue (Kobe university), Yusuke Uchiyama (Kobe university) |
| Part | | OS11 | 4085 | | Yusuke Uchiyama (Kobe University), Miyuki Kawakami (Kobe University) |
| 14-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1- | | OS11 | 4153 | Aerodynamics Analysis of a Ram-air Parachute | Takuya Terahara (Waseda University), Kenji Takizawa (Waseda University), Tayfun E. Tezduyar (Rice University) |
| Service Main Liverancy (March Have Designed in Applications of Service March Liverancy (March Have Designed in Applications (March Designed in Applications (M | | OS11 | 4167 | Accelerated Multi GPU Simulation for Tsunami runnup at Toyama-bay | CORPORATION), Tsukasa Aso (Dpt. of Electronics & Computer Eng., NIT Toyama-College, Japan), Yuki Ueda (School for El |
| Secure 15 (1997) 17 (1997) 20 (1997) | | OS11 | 4170 | | Sciences, Kobe University), Shuzo Takagi (Okayama Prefectural Technology Center for Agriculture, Forestry and Fisheries, R |
| International Control of Control | | OS11 | 4174 | Quantitative evaluation for two dimensional rising bubble dynamics by FreeFem++ | |
| Description of the company of the co | | OS11 | 4090 | Numerical simulation of water wave run-up and impact on structures | |
| Section 5 of the control of the cont | | OS11 | 4237 | | Akira Maruoka (National Institute of Technology, Hachinohe College) |
| Section 2 Section 2 Section 2 Section 3 Section 4 Section 3 Section 4 Section 4 Section 4 Section 5 Section 6 | | OS11 | 4055 | | Chiaki Kino (The Institute of Applied Energy) |
| Colin 4317 Numerical simulation for the forced Glarder equation Security Secur | | OS11 | 4286 | | |
| Session 24 1100-120, 11 0.cd OS11 435 Selection by Taxamarian or a few dates of usual measurement requestor. OS12 435 Selection by Taxamarian or a few dates of usual measurement of the part certificate end of the logs of the leafund frough. Second of the leafund frough of the leafund | | OS11 | 4315 | Multiscale Thermo-Fluid Analysis of a Tire | Takashi Kuraishi (Waseda University), Kenji Takizawa (Waseda University), Tayfun E. Tezduyar (Rice University) |
| 1100-12:00, 13 Oct. OS11 415 Seed on the great earthquake oceanors along the Narkari Trough. OS12 417 Pales Element Analysis of Acoustic Velocity Model OS14 417 Pales Element Analysis of Acoustic Velocity Model OS15 description of the Seed of Narkari Section of Narkari Sections, Model Preventing Oscillators (Narkari Sections) (Nar | | OS11 | 4317 | Numerical simulations for the forced Gardner equation | |
| Sension 6 1.00-12.00, 12 OS12 4321 Deposition or and promise in employee and vivous process or a sension of the control of position or any of | | OS11 | 4351 | | University), Shunichi Koshimura (International Research Institute of Disaster Science, Tohoku University), Yuuki Taniguchi (Gr |
| Session 1 Session 1 OS12 4358 Realization of Robotic Yoyo Operation Service | | OS11 | 4117 | Finite Element Analysis of Acoustic Velocity Model | |
| Measurine Vision Programment of Civil and Environmental Engineering, Facility of Section 4. Engineering, Facility of Tokyo), Tomonor Yamada (RACE, University) of Tokyo). Engineering Facility of Tokyo), Tomonor Yamada (RACE, University) of Tokyo). Engineering Facility of Tokyo), Tomonor Yamada (RACE, University) of Tokyo). Engineering Facility of Tokyo), Tomonor Yamada (RACE, University) of Tokyo). Engineering Facility of Tokyo), Tomonor Yamada (RACE, University) of Tokyo). Engineering Facility of Tokyo). Engineering Facility of Tokyo). Engineering Facility of Tokyo) and Engineering Facility of Tokyo). Engineering Facility of Engineering Facility of Tokyo). Engineering Facility of Eng | | OS11 | 4221 | | Koji-Kodama (Chuo-University), Katsumi-Seki-(Chuo-University), Taro-Arikawa (Chuo-University) |
| Session 2 9.45 10.45, 12. Oct. Session 2 9.45 10.45, 12. Oct. OS12 4322 Motion generation of persistatic mobile robot with particle swarm optimization of state of the control of persistatic mobile robot with particle swarm optimization of state of the control of persistatic mobile robot with particle swarm optimization of state of the control of persistatic mobile robot with particle swarm optimization of state of the control of persistatic mobile robot with particle swarm optimization of state of the control of persistatic mobile robot with particle swarm optimization of state of the control of persistatic mobile robot with particle swarm optimization of state of the control of persistatic mobile robot with particle swarm optimization of state of the control of persistatic mobile robot with particle swarm optimization of state of the control of persistatic mobile robot with particle swarm optimization of state of the control of state of the control of persistatic mobile robot with particle swarm optimization by MIMO-NDARX Model Using A Electromogram Session 16 OS12 4318 Modeling and dynamic analysis of the bicycle for reducing the risk of failing over the protein of the center of granty Session 10 OS12 4326 Realization of Robots of State on the position of the center of granty OS12 4327 Realization of Robots of State on the center of granty Takuma Nemotic (Tokyo Denis University), Registe Eleman Mohant (Singapore University of Technology for Future Life, Tokyo Denis University) Takuma Nemotic (Tokyo Denis University), Registe Elara Mehant (Singapore University of Technology for Future Life, Tokyo Denis University) Takuma Nemotic (Tokyo Denis University), Registe Elara Mehant (Singapore University) of Technology for Future Life, Tokyo Denis University) Takuma N | 14:45-15:25, 13 Oct. | OS11 | 4441 | Reproduce Calculation of the Bridge Girder Outflow by CADMAS-STR | |
| Session 2 3.45-10.45, 12 Oct. OST2 4300 Non-invasive continuous blood pressure monitoring at radial artery Talkahiro Homma (Tokyo Denki University), Nonhiro Kamamichi (Tokyo Denki University) Talkahiro Homma (Tokyo Denki University), Nonhiro Kamamichi (Tokyo Denki University) | S12: Motion Dynamics in H | lumans, Anir | nals an | nd Robots | |
| 9.45-10.45, 12 Oct. US12 4309 Non-invasive continuous blood pressure monitoring at radial artery | | OS12 | 4068 | Performance Evaluation of Flapping Flight Considering Passive Feathering Using Partitioned Iterative Coupling Method | |
| OS12 431 Upper-limbs Movement Estimation by MIMO-NDARX Model Using A Electromyogram organizering king monglarts institute of technology ladkrabang) OS12 4311 Upper-limbs Movement Estimation by MIMO-NDARX Model Using A University), Shoshior Haidseyama (Department of Robotics and Mechatronics, School of Future Science, Tokyo Denki University), Shoshior Haidseyama (Pagnatment of Robotics and Mechatronics, School of Future Science, Tokyo Denki University), Shoshior Haidseyama (Pagnatment of Robotics and Mechatronics, School of Future Science, Tokyo Denki University), Masaki Izusus (Department of Robotics and Mechatronics, School of Future Science, Tokyo Denki University), Masami Iwase (Department of Robotics and Mechatronics, School of Future Science, Tokyo Denki University), Masami Iwase (Department of Robotics and Mechatronics, School of Future Science, Tokyo Denki University), Masami Iwase (Department of Robotics and Mechatronics, School of Future Science, Tokyo Denki University), Masami Iwase (Department of Robotics and Mechatronics, School of Science and Technology for Future Life, Notyo Denki University), Masami Iwase (Department of Robotics, and Mechatronics, Graduate School of Science and Technology for Future Life, Notyo Denki University), Masami Iwase (Department of Robotics and Mechatronics, Graduate School of Science and Technology for Future Life, Notyo Denki University), Masami Iwase (Department of Robotics and Mechatronics, Graduate School of Science and Technology for Future Life, Notyo Denki University), Masami Iwase (Department of Robotics and Mechatronics, Graduate School of Science and Technology for Future Life, Notyo Denki University), Masami Iwase (Department of Robotics and Mechatronics, Graduate School of Science and Technology for Future Life, Notyo Denki University), Masami Iwase (Department of Robotics and Mechatronics, Graduate School of Science and Technology for Future Life, Tokyo Denki University), Masami Iwase (Department of Robotics and Mechatronics, Craduate School of Science and | | OS12 | 4282 | | Takahiro Homma (Tokyo Denki University), Norihiro Kamamichi (Tokyo Denki University) |
| Session 6 11:00-12:00, 12 Oct. OS12 4318 Modeling and dynamic analysis of the bicycle for reducing the risk of falling over OS12 4318 Modeling and dynamic analysis of the bicycle for reducing the risk of falling over OS12 4328 Rolling locomotion control of a bic-inspired reconfigurable quadruped robot based on the position of the center of gravity OS12 4324 Realization of Robotic Yoyo Operation based on Operation Session 10 14:45-15-45, 12 Oct. OS12 4326 Design Method of Decentralized Control System for Multi-legged Robot Session 34 9:45-10-45, 14 Oct. OS13 4327 Efficiency operation is definite volume method for extended porous medium equations and its application to identifying physical properties of a fin non-woven fibrous sheet Session 34 9:45-10-45, 14 Oct. OS13 4352 Double-T Stub Microstrip UWB Slot Antenna OS14 4352 Double-T Stub Microstrip UWB Slot Antenna University), Shopsino Hatakeyama (Department of Robotics and Mechatronics, School of Science, Tokyo Denki University), Masaami Iwase (Department of Robotics and Mechatronics, Graduate School of Science and Technology for Future Life), Tokyo Denki University), Pagies Eliara Mohan (Singapore University of Technology and Design), Masaami Iwase (Department of Robotics and Mechatronics, Graduate School of Science and Technology for Future Life), Ozek Mayu (Department of Robotics and Mechatronics, Graduate School of Science and Technology for Future Life), Vase Masami (Department of Robotics and Mechatronics, Graduate School of Science and Technology for Future Life, Nave Masami (Department of Robotics and Mechatronics, Graduate School of Science and Technology for Future Life, Nave Masami (Department of Robotics and Mechatronics, Graduate School of Science and Technology for Future Life, Tokyo Denki University), Shockino Hatakeyama (Department of Robotics and Mechatronics, Undergraduate School of Science and Technology for Future Life, Tokyo Denki University), Shockino Hatakeyama (Department of Robotics and Mechatronics, Undergraduate School of | | OS12 | 4309 | Non-invasive continuous blood pressure monitoring at radial artery | engineering king mongkut's institute of technology ladkrabang) |
| 11:00-12:00, 12 Oct. OS12 4318 Modeling and dynamic analysis of the Dicycle for featuring over University), Masami Iwase (Department of Robotics and Mechatronics, School of Future Science, Tokyo Denki University) OS12 4322 Rolling locomotion control of a bio-inspired reconfigurable quadruped robot based on the position of the center of gravity OS12 4324 Realization of Robotic Yoyo Operation based on Operation Session 10 14-45-15-45, 12 Oct. OS12 4326 Design Method of Decentralized Control System for Multi-legged Robot OS12 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 4326 Design Method of Decentralized Control System for Multi-legged Rob | | OS12 | 4311 | | University), Shoshiro Hatakeyama (Department of Robotics and Mechatronics, School of Future Science, Tokyo Denki University), |
| OS12 4324 Realization of Robotic Yoyo Operation based on Operation Session 10 14:45-15-45, 12 Oct. OS12 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 4326 Design Method of Decentralized Control System for Multi-legged Robot OS13 455-10-45, 14 Oct. OS13 4526 Design Method of Decentralized Control System for Multi-legged Robot Session 34 9:45-10-45, 14 Oct. OS13 4270 Efficient simulation method for quantum build-up and decay processes in resonant Session 34 9:45-10-45, 14 Oct. OS13 4326 Double-T Stub Microstrip UWB Slot Antenna OS13 4327 Double-T Stub Microstrip UWB Slot Antenna OS13 4328 Double-T Stub Microstrip UWB Slot Antenna OS14 A329 Double-T Stub Microstrip UWB Slot Antenna OS15 A352 Double-T Stub Microstrip UWB Slot Antenna OS16 A352 Double-T Stub Microstrip UWB Slot Antenna OS17 Bangkok, Thailand), Neppin Anantrasirchai (The Institute or the Promotion of Teachnology Ladkrabang, Bangkok, Thailand), Pathon Thani, Thailand), Neppin Anantrasirchai (The Institute for the Promotion of Teachnology Ladkrabang and Technology Canbrain Standard). Pathon Thani, Thailand), Neppin Anantrasirchai (The Institute for the Promotion of Teachnology Ladkrabang, Bangkoks Thailand), Neppin Anantrasirchai (The Institute for the Promotion of Teachnology Canbrain Science and Technology Canbrain Chemology Ladkrabang and Technology Ladkrabang and Technology Ladkrabang and Technology Ladkrabang and Technology Ladkrabang Chepatiment of Technology Ladkrabang and Technology Canbrain Chemology Ca | | OS12 | 4318 | Modeling and dynamic analysis of the bicycle for reducing the risk of falling over | |
| Session 10 14:45-15:45, 12 Oct. OS12 4324 Realization of Robotic Yoyo Operation based on Operation Hokuto (Department of Robotics and Mechatronics, Graduate School of Science and Technology for Future Life), Wase Masami (Dep Robotics and Mechatronics, Graduate School of Science and Technology for Future Life), wase Masami (Dep Robotics and Mechatronics, Graduate School of Science and Technology for Future Life) Welchi Onodera (Major of Robotics and Mechatronics, Graduate School of Science and Technology for Future Life, Tokyo Den University), Masaki Izutsu (Department of Robotics and Mechatronics, Undergraduate School of Science and Technology for Future Life, Tokyo Den University), Shoshiro Hatakeyama (Department of Robotics and Mechatronics, Undergraduate School of Science and Technology for Four Tokyo Denki University), Shoshiro Hatakeyama (Department of Robotics and Mechatronics, Undergraduate School of Science and Technology for Four Four Polyone Future Life, Tokyo Denki University), Shoshiro Hatakeyama (Department of Robotics and Mechatronics, Undergraduate School of Science and Technology for Four Four Four Polyone Future Life, Tokyo Denki University), Shoshiro Hatakeyama (Department of Robotics and Mechatronics, Undergraduate School of Science and Technology for Four Four Four Four Four Four Four Fo | | OS12 | 4322 | | |
| OS12 4326 Design Method of Decentralized Control System for Multi-legged Robot University, Massaki Eutsus (Department of Robotics and Mechatronics, Graduate School of Science and Technology for Flore University), Shoshiro Hatakeyama (Department of Robotics and Mechatronics, Undergraduate School of Science and Technology for Flore Tokyo Denki University), Shoshiro Hatakeyama (Department of Robotics and Mechatronics, Undergraduate School of Science Technology for Flore University), Shoshiro Hatakeyama (Department of Robotics and Mechatronics, Undergraduate School of Science Technology for Flore University), Shoshiro Hatakeyama (Department of Robotics and Mechatronics, Undergraduate School of Science Technology for Flore University), Flore University (Paculty of Life and Environmental Science, Shimane University), Yuma Ito (Graduate School of Life and Environmental Science, Shimane University), Yuma Ito (Graduate School of Life and Environmental Science, Shimane University), Flore University, Not (Faculty of Life and Environmental Science, Shimane University), Flore University, Not (Faculty of Life and Environmental Science, Shimane University), Flore University, Not (Faculty of Life and Environmental Science, Shimane University), Flore University, Not (Faculty of Life and Environmental Science, Shimane University), Flore University, Not (Faculty of Life and Environmental Science, Shimane University), Flore University, Not (Faculty of Life and Environmental Science, Shimane University), Flore University, Not (Faculty of Engineering, University of Fuku), Norifumi Yamada (Information Science, Graduate School of Engineering, University of Fuku), Norifumi Yamada (Information Science, Graduate School of Engineering, University of Fuku), Norifumi Yamada (Information Science, Graduate School of Engineering, University of Fuku), Norifumi Yamada (Information Science, Graduate School of Engineering, King Mongkut's Institute of Technology Ladkrabang, Bangkok, Thailand), Paloron Rak (Department of Electronic and telecommunica | | OS12 | 4324 | Realization of Robotic Yoyo Operation based on Operation | Hokuto (Department of Robotics and Mechatronics, Graduate School of Science and Technology for Future Life), Ozeki Mayui (Department of Robotics and Mechatronics, Graduate School of Science and Technology for Future Life), Iwase Masami (Dep |
| A stable finite volume method for extended porous medium equations and its application to identifying physical properties of a thin non-woven fibrous sheet (Faculty of Life and Environmental Science, Shimane University), Lohiro Kita (Faculty of Life and Environmental Science, Shimane University), Kot. (Faculty of Life and Environmental Science, Shimane University), Kot. (Faculty of Life and Environmental Science, Shimane University), Lohiro Kita (Faculty of Life and Environmental Science, Shimane University), Kot. (Faculty of Life and Environmental Science, Shimane University), Kot. (Faculty of Life and Environmental Science, Shimane University), Kot. (Faculty of Life and Environmental Science, Shimane University), Kot. (Faculty of Life and Environmental Science, Shimane University), Kot. (Faculty of Life and Environmental Science, Shimane University), Kot. (Faculty of Life and Environmental Science, Shimane University), Kot. (Faculty of Environmental Science, Shimane University), Kot. (Faculty | | OS12 | 4326 | Design Method of Decentralized Control System for Multi-legged Robot | University), Masaki İzutsu (Department of Robotics and Mechatronics, Undergraduate School of Science and Technology for F Tokyo Denki University), Shoshiro Hatakeyama (Department of Robotics and Mechatronics, Undergraduate School of Science |
| OS13 4027 Asstering continue fourier interest of the Kenneto Dricks Remote protos interestinal and application to identifying physical properties of a thin non-woven fibrous sheet application to identifying physical properties of a thin non-woven fibrous sheet (Faculty of Life and Environmental Science, Shimane University), Kot (Faculty of Life and Environmental Science, Shimane University), Kot (Faculty of Life and Environmental Science, Shimane University), Kot (Faculty of Life and Environmental Science, Shimane University), Kot (Faculty of Life and Environmental Science, Shimane University), Kot (Faculty of Life and Environmental Science, Shimane University), Kot (Faculty of Life and Environmental Science, Shimane University), Kot (Faculty of Life and Environmental Science, Shimane University), Kot (Faculty of Life and Environmental Science, Shimane University), Kot (Faculty of Life and Environmental Science, Shimane University), Kot (Faculty of Life and Environmental Science, Shimane University), Kot (Faculty of Life and Environmental Science, Shimane University), Kot (Faculty of Life and Environmental Science, Shimane University), Kot (Faculty of Life and Environmental Science, Shimane University, Kot (Faculty of Life and Environmental Science, Shimane University), Kot (Faculty of Life and Environmental Science, Shimane University). | DS13: 1D Simulation | | | | Hildright Washing (Faculty of He and Facinese) and Aller |
| Session 34 9:45-10:45, 14 Oct. RS16 US13 4240 Uunneling Graduate School of Engineering, University of Fukui) Tuanjai Archevapanich (Faculty of Engineering, King Mongkut's Institute of Technology Ladkrabang, Bangkok, Thailand), May Letrwatechakut (Faculty of Engineering, King Mongkut's Institute of Technology Ladkrabang, Bangkok, Thailand), Patoon Rak (Department of Electronic and telecommunication Engineering, Engineering, Engineering, Engineering, Engineering, Engineering, Engineering, Engineering, King Mongkut's Institute of Technology Ladkrabang, Bangkok, Thailand), Patron Rak | | OS13 | 4027 | | Environmental Science, Shimane University), Ichiro Kita (Faculty of Life and Environmental Science, Shimane University), Kot |
| RS16 RS17 RS17 RS17 RS17 RS18 | | OS13 | 4240 | | Graduate School of Engineering, University of Fukui) |
| | | RS16 | 4352 | Double-T Stub Microstrip UWB Slot Antenna | Lertwatechakul (Faculty of Engineering, King Mongkut's Institute of Technology Ladkrabang, Bangkok, Thailand), Paitoon Rak (Department of Electronic and telecommunication Engineering, Faculty of Engineering Rajamangala University of Technology Thanyaburi, Pathum Thani, Thailand), Noppin Anantrasirichai (The Institute for the Promotion of Teaching Science and Techni (IPST) Bangkok, Thailand), Vanvisa Chutchavong (Faculty of Engineering, King Mongkut's Institute of Technology Ladkraban |

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| S15: Complex Networks an | u Complex S | ysiem | | |
| Session 44 13:30-14:50, 14 Oct. | OS15 | 4184 | Speedup of Dynamic Route Search for Large-scale Microscopic Simulation | Naoki Mita (Department of Systems Innovation, School of Engineering, The University of Tokyo), Hideaki Uchida (Department Systems Innovation, School of Engineering, The University of Tokyo), Hideaki Fujii (Department of Systems Innovation, School Engineering, The University of Tokyo), Shinobu Yoshimura (Department of Systems Innovation, School of Engineering, The University of Tokyo) |
| | OS15 | 4214 | The learning property of spike-timing-dependent plasticity in neural network with the subthreshold membrane resonance | Siu Kang (Department of Bio-Systems Engineering, Graduate School of Science and Engineering, Yamagata University), Mas Minamisawa (IBsystem Co., Ltd), Kana Kimura (Department of Bio-Systems Engineering, Graduate School of Science and En Yamagata University), Taishi Matsumura (Department of Bio-Systems Engineering, Graduate School of Science and Engineer Yamagata University), Taitsu of Kiajima (Malaysia-Japan International Institute of Thechnology), Tetsuya Yuasa (Department of Systems Engineering, Graduate School of Science and Engineering, Yamagata University) |
| | OS15 | 4306 | Graph based structure analysis of the network of n-Chinese-character compound words in the Japanese language | Tetsuo Imai (Department of Informatics, Tokyo University of Information Sciences), Kousuke Yoshizawa (Department of Inform Tokyo University of Information Sciences), Shuhei Miyake (Department of Informatics, Tokyo University of Information Science |
| | OS15 | 4335 | The Design and Simulation of Communication Network in Railway systems | Totsawat Cheewatanalerdkul (Faculty of Engineering, King Mongkut's Institute of Technology Ladkrabang), Thanavit Anuwong (Faculty of Engineering, King Mongkut's Institute of Technology Ladkrabang), Alongkon Vijittanasam (Faculty of Engineering, I Mongkut's Institute of Technology, Ladkrabang), Boonchana Purahong (Faculty of Engineering, King Mongkut's Institute of Technology Ladkrabang), Vanvisa Chutchavong (Faculty of Engineering, King Mongkut's Institute of Technology Ladkrabang), |
| S16: Image and Video Proc | essing | | | |
| | OS16 | 4080 | Simultaneous Estimation of Missing Pixels and Segmentations | Tomohiro Takahashi (Tokyo University of Science), Katsumi Konishi (Kogakuin University), Kazunori Uruma (Tokyo University Science), Toshihiro Furukawa (Tokyo University of Science) |
| Session 38 11:00-12:00, 14 Oct. | OS16 | 4123 | Improvement of Crater Detection using Principal Component Analysis Considering the Object Shape | Misako Moribe (Graduate School of Science and Technology, Meiji University, Japan), Tatsuya Takino (Graduate School of Sc and Technology, Meiji University, Japan), Izuru Nomura (Graduate School of Science and Technology, Meiji University, Japan Kamata (School of Science and Technology, Meiji University, Japan) |
| | OS16 | 4191 | A Robust Method for Estimating Human Count from Complex Traffic Scene | Kazuhiko Hamamoto (Tokai University, Japan), Thanh-sach Le (Ho Chi Minh City University of Technology, Vietnam), Chi-kier (Ho Chi Minh City University of Technology, Vietnam) |
| | OS16 | 4218 | Depth Image Recovery Algorithm Using Image Segmentation and Sparse Optimization | Kazunori Uruma (Tokyo University of Science), Katsumi Konishi (Kogakuin University), Tomohiro Takahashi (Tokyo University Science), Toshihiro Furukawa (Tokyo University of Science) |
| | OS16 | 4232 | Cancellation of Show-through effect Using Kalman Filter | Ryu Nagayasu (Tokyo University of Science), Nari Tanabe (Tokyo University of Science, SUWA), Toshihiro Furukawa (Tokyo of Science) |
| Session 42 13:30-14:50, 14 Oct. | OS16 | 4419 | Adaptive Lp Norm Minimization Approach to Intra-Frame Super-Resolution | Misuhiro Komiya (Department of Management Science, Tokyo University of Science), Katsumi Konishi (Department of Compu Science, Kogakuin University), Kazunori Uruma (Department of Management Science, Tokyo University of Science), Tomohirr Takahashi (Department of Management Science, Tokyo University of Science), Toshihiro Furukawa (Department of Managem Science, Tokyo University of Science) |
| | OS16 | 4424 | Video colorization algorithm using Lp norm minimization | Osamu Yamada (Department of Management Science, Tokyo University of Science), Kazunori Unuma (Department of Manage Science, Tokyo University of Science), Katsumi Konishi (Department of Computer Science, Kogakuin University), Tomohiro Ta (Department of Management Science, Tokyo University of Science), Toshihiro Furukawa (Department of Management Science University of Science) |
| S17: Cognitive Modeling an | ıd Visualizati | on | | |
| | OS17 | | A study on Communication Tools Using Evaluation Grid Method | Nobuyuki Kukimoto (Yousuke Onoue), Koji Koyamada |
| Session 28 14:45-15:45, 13 Oct. | OS17 | 4415 | Network Coarse-Graining for Evaluation Structures | Yosuke Onoue (Kyoto University), Nobuyuki Kukimoto (Kyoto University), Naohisa Sakamoto (Kyoto University), Koji (Koyama |
| | OS17 | 4454 | Word cloud visualization of Evaluation Structures focusd on Location | Keita Ozawa (Graduate School of Engineering, Kyoto University), Naohisa Sakamoto (Institute for Liberal Arts and Sciences, P University), Koji Koyamada (Academic Center for Computing and Media Studies, Kyoto University) |
| 18: Simulation Technology | y in Origami | | | |
| | OS18 | 4144 | Design Concepts of Displacement Amplification Mechanism Using Folding Patterns of Origami | Sachiko Ishida (Department of Mechanical Engineering, Meiji University), |
| Session 36 9:45-10:45, 14 Oct. | OS18 | 4173 | Simulation of folding process by two robotic hands | Phuong Thao Thai (Graduate School of Advanced Mathematical Sciences, Meiji University), Maria Savchenko (Graduate Scho Advanced Mathematical Sciences, Meiji University), Ichiro Hagiwara (Graduate School of Advanced Mathematical Sciences, N University) |
| | OS18 | 4245 | 3D "portrait" object reconstruction from a single | Yujing Liao (Institute for Advanced Study of Mathematical Sciences, Meiji University), Maria Savchenko (Institute for Advanced Mathematical Sciences, Meiji University), Ichiro Hagiwara (Institute for Advanced Study of Mathematical Sciences, Meiji Unive |
| Session 40 | OS18 | 4266 | Origami-based Design for the sandwich core structure | Yang Yang (Graduate School of Advanced Mathematical Sciences, Meiji University), Maria Savchenko (Graduate School of Ad Mathematical Sciences, Meiji University), Ichiro Hagiwara (Graduate School of Advanced Mathematical Sciences, Meiji Univer |
| 11:00-11:40, 14 Oct. | OS18 | 4293 | Design and Construction of a System for Paper Folding using LEGO NXT | Julian Romero (Interfocus Inc. & Meiji Institute for Advanced Study of Mathematical Sciences, Meiji University, Japan), Luis Di (Interfocus Inc. & Meiji Institute for Advanced Study of Mathematical Sciences, Meiji University, Japan), Ichiro Hagiwara (Meiji Advanced Study of Mathematical Sciences, Meiji University, Japan) |
| 19: Visualization and Visu | al Analytics | for Ear | th Scientific and Environmental Simulations (co-organized by the Visualization Socie | |
| Session 15 16:00-17:20, 12 Oct. | OS19 | 4089 | High-resolution large-eddy simulation for analyzing cooling effect of trees in an urban green space | Keigo Matsuda (Center for Earth Information Science and Technology (CEIST), Japan Agency for Marine-Earth Science and T (JAMSTEC)). Toru Sugiyama (Center for Earth Information Science and Technology (CEIST), Japan Agency for Marine-Earth and Technology (JAMSTEC)), Psy Onishis (Center for Earth Information Science and Technology (CEIST), Japan Agency for N Earth Science and Technology (JAMSTEC)), Shintaro Kawahara (Center for Earth Information Science and Technology (JAMSTEC)), Furniaki Araki (Center for Earth Information Science and Technology (JAMSTEC)), Furniaki Araki (Center for Earth Information Science and Technology (JAMSTEC)), Nelko Takahashi (Center for Earth Information Science and Technology (JAMSTEC)) and Technology (JAMSTEC)) |
| | OS19 | 4264 | Realistic representation of atmospheric clouds in Google Earth | Shintaro Kawahara (JAMSTEC), Ryo Onishi (JAMSTEC), Koji Goto (NEC Corporation), Keiko Takahashi (JAMSTEC) |
| | OS19 | 4267 | Flow Field Segmentation Method Using Multi-Parameter | Yumi (Yamashita), Fumiaki (Araki), Daisuke (Matsuoka), Takayuki (Itoh) |
| | OS19 | 4329 | Extraction, classification and visualization of cloud simulated by atmoshperic general circulation model | Daisuke Matsuoka (Japan Agency for Marine-Earth Science and Technology), Kazuyoshi Oouchi (Japan Agency for Marine-E: Science and Technology) |

| Regular Session | | | | | | | |
|-----------------------------------|------|------|--|--|--|--|--|
| | RS1 | 4312 | Design Method of Optimal H2 Integral Servo System with Derivative State Constraints | Noriyuki Komine | | | |
| Session 1 9:45-10:45, 12 Oct. | RS1 | 4383 | All-Optical Switching in PANDA Ring Resonator by Carrier Injection | Saysamone Soysouvanh (Hybrid Computing Research Laboratory, Faculty of Engineering, King Mongkut's Institute of Techno Ladkrabang, Bangkok 10520, Thailand), Khanthanou Luangxaysana (Hybrid Computing Research Laboratory, Faculty of Engi King Mongkut's Institute of Technology Ladkrabang, Bangkok 10520, Thailand), Prapas Phongsanam (Hybrid Computing Rese Laboratory, Faculty of Engineering, King Mongkut's Institute of Technology, Ladkrabang, Bangkok 10520, Thailand), Somask N (Hybrid Computing Research Laboratory, Faculty of Engineering, King Mongkut's Institute of Technology, Ladkrabang, Bangko Thailand), Masahiro Yoshida (Department of Embedded Technology, School of Information and Telecommunication En Tokai University, Japan), Noriyuki Komine (Department of Embedded Technology, School of Information and Telecommunication En Tokai University, Japan), Masaakir Fukuhara (Department of Embedded Technology, School of Information and Telecommunic Engineering, Tokai University, Japan), Precebar Vupapin (Nanoscale Science and Engineering Research Alliance, Faculty of S King Mongkut's Institute of Technology Ladkrabang, Bangkok 10520, Thailand) | | | |
| | RS16 | 4037 | Geant4 Monte Carlo simulation for beta ray spectra in liquid scintillation counter for estimating detection efficiency | Yuki Tsubouchi (Advanced Course, National Institute of Technology, Toyama College), Tsukasa Aso (Electronics and Comput Engineering, National Institute of Technology, Toyama College), Masanori Hara (Hydrogen Isotop Research Center, Universit) Toyama), Miki Shoji (Life Science Research Center, Universit) of Toyama), Takayoshi Furusawa (Measuring Systems Enginer Department, Hitachi Aloka Medical Ltd.), Tomoyuki Yoshimura (Measuring Systems Engineering Department, Hitachi Aloka Medical Ltd.), Tomoyuki Yoshimura (Measuring Systems Engineering Department, Hitachi Aloka Medical Ltd.), Riona Benii (Advanced Course, N. Institute of Technology, Toyama College), | | | |
| | RS16 | 4038 | Geant4 Monte Carlo simulation for Iodine-125 spectrum in liquid scintillation | Riona Benii (Advanced Course, National Institute of Technology, Toyama College), Tsukasa Aso (Electronics and Computer Engineering, National Institute of Technology, Toyama College), Miki Shoji (Life Science Research Center, University of Toyar Masanori Hara (Hydrogen Isotope Research Center, University of Toyaram), Stakyoshi Furusawa (Measuring Systems Engine Department, Hitachi Aloka Medical, Ltd.), Tomoyuki Yoshimura (Measuring Systems Engineering Department, Hitachi Aloka Meludi, Yuki Kato (Measuring Systems Engineering Department, Hitachi Aloka Medical, Ltd.), Yuki Tsubouchi (Advanced Cours Institute of Technology, Toyama College) | | | |
| Session 5 11:00-12:20, 12 Oct. | RS16 | 4059 | Resilience Assessment of Telephone Communication Network | Dingding Chao (Department of Systems Innovation, Graduate School of Engineering, the University of Tokyo), Yuki Watanabe (Department of Systems Innovation, Graduate School of Engineering, the University of Tokyo), Taro Kanno (Department of Sy Innovation, Graduate School of Engineering, the University of Tokyo), Kazuo Furuta (Resilience Engineering Research Center Department of Technology Management for Innovation, Graduate School of Engineering, the University of Tokyo) | | | |
| | OS16 | 4165 | | Vanvisa Chutchavong (Faculty of Engineering, King Mongkut's Institute of Technology Ladkrabang, 1 Chalongkrung Rd., Ladk Bangkok 10520, Thailand) | | | |
| | RS16 | 5110 | Sound Field Estimation Using Double Nearfield Holography Method | Masao Nagamatsu (Hokkaido University of Science) | | | |





1階 平面図 270817 富山国際会議場 地下駐車場 入口 事務所 **** 避難階段 荷物用 EV 中央監視室 応接コーナー 白黒1枚/10円 カラー1枚/50円 課金コピー機 カウンター 斜路 搬出入口 【記・机・ 受付】 ・机12 内線設置 NO126 【記名台】 ・机4 避難 EV HC トイレ ●仮設分電盤 女子トイレ 分煙室 男子トイレ нс トイレ 自動販売機 デジタルサイネージ アートサロン 交流ギャラリー 【おみやげ販売】 カウンター エスカレータ ΕV → 【観光デスク】 カフェ・ドゥ・ミュゼ 東階段 南階段